

# **Characterizing Infrared (IR) Sensor for Hypervelocity Asteroid Intercept Vehicle (HAIV)**

**Dec14-12**

Client - Dr. Bong Wie  
Advisor - Dr. Meng Lu

Leader - Sean Nichols  
Webmaster - Yishu Mei  
Communication Master - Chi Hoe How

# Purpose

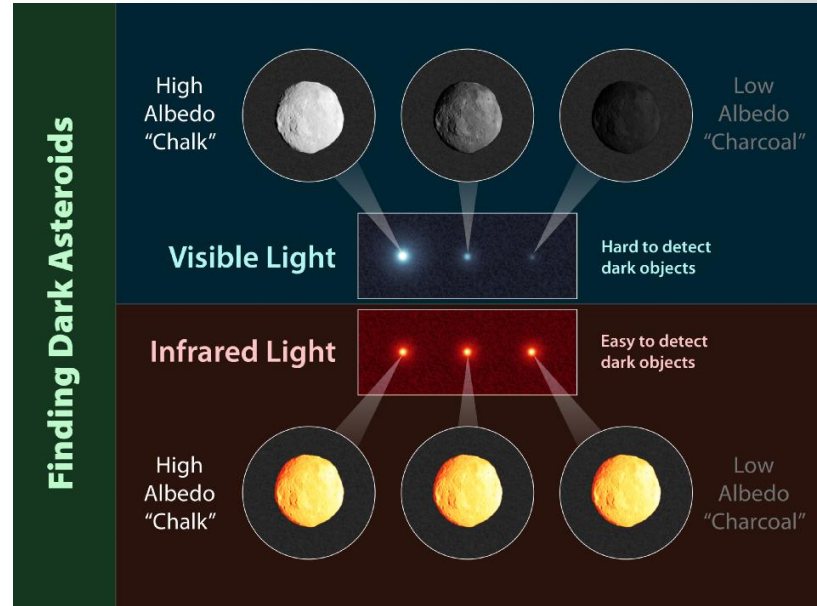
**Background :** Client's team has developed asteroid simulations

**Problem :** The feasibility of such a system was unknown

- IR technologies
- IR optics
- Distance of detection

**Solution :** We are employed to:

- Research technologies
- Design such a system
- Perform cost analysis

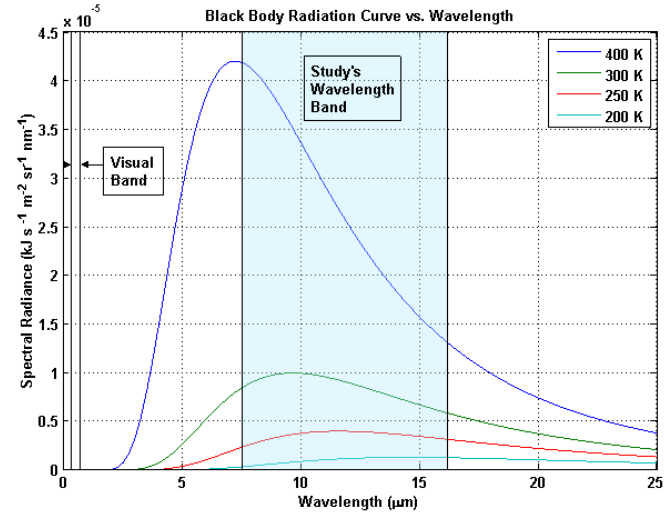


Source: nasa.gov

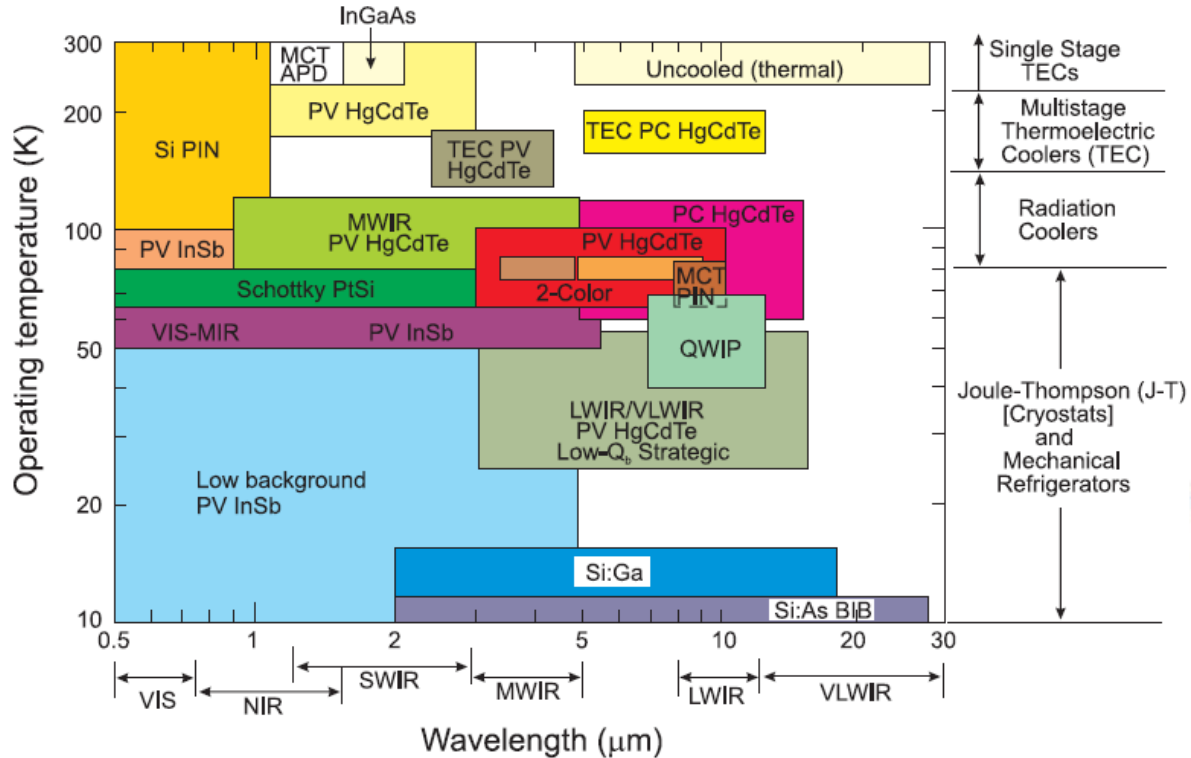
# Initial Meetings

## Early meetings with client

- Asteroid Parameters
  - Size (~ 50 m)
  - IR emission (~ 8 to 14  $\mu\text{m}$ )
- HAIV Parameters
  - Speed of approach (~10 km/s)
  - Time of detection (1 hour)
- Sensor types
  - Photon detector (cooling, high resolution, high speed, expensive)
  - Thermal detector (uncooled, lower resolution, slow speed, lower price)



# Sensor Types



# Initial Plan

Our initial idea

- Experiment Proposal
- Not within budget
- Hard to do

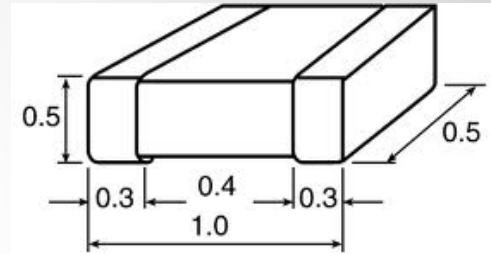
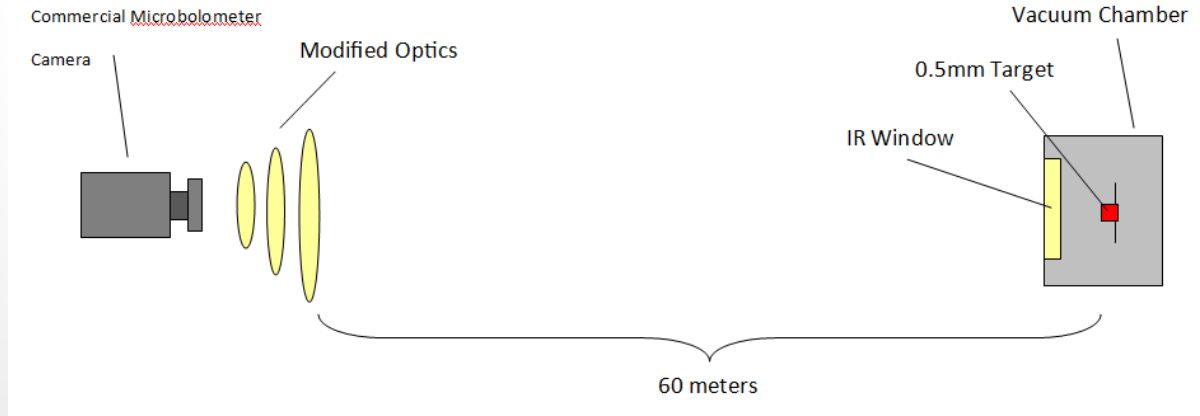


Image not to scale!

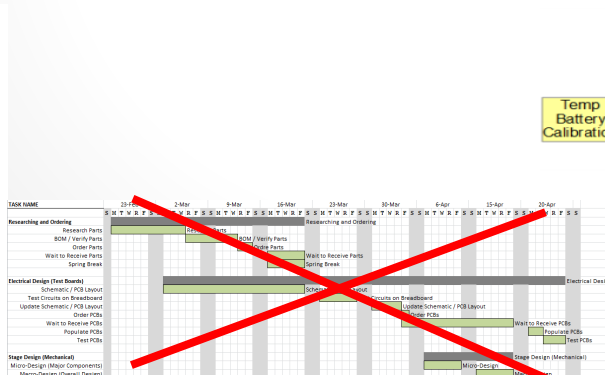
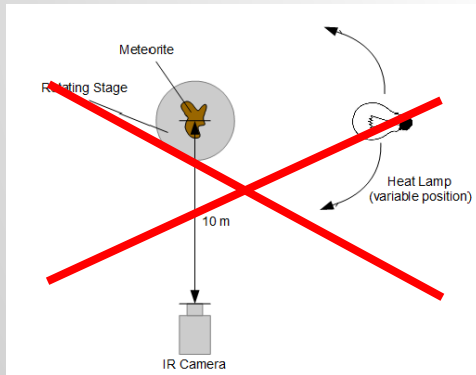
0402



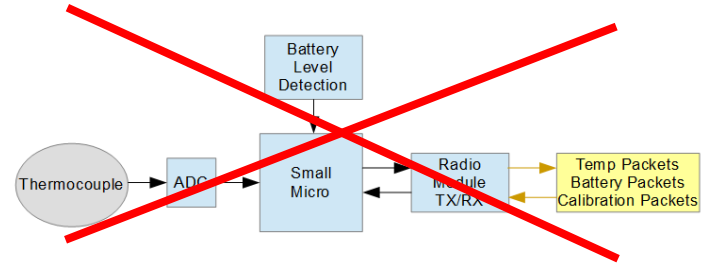
# Next Plan

## Our next plan - the turn table

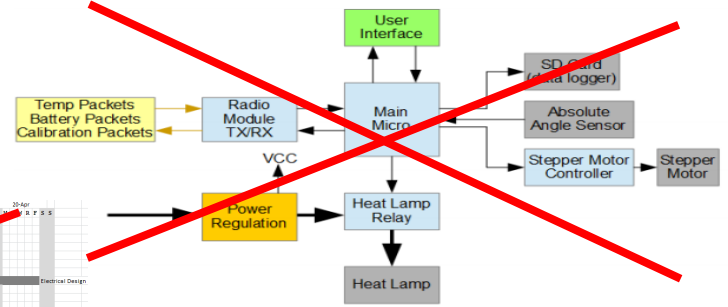
- Heat object to specific temp
- Thermal distributions
- Differing light angles
- Disagreement



Block Diagram : Battery Power



Block Diagram : Main Power



# New Plan

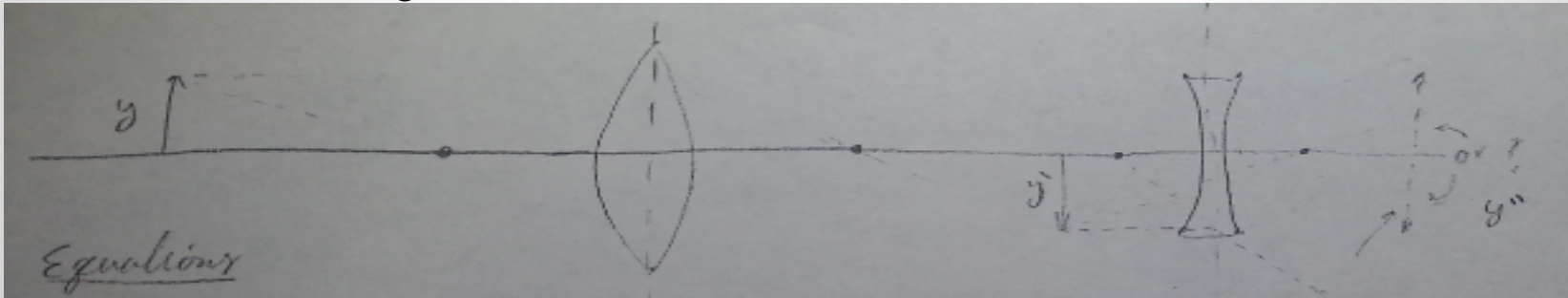
Design an optics system

- IR telescope design
- Simulations
- Differing parameters
  - Thermal Camera
  - Photon Camera
- Cost analysis
  - IR lenses / mirrors
  - Camera
  - Cooling

# New Plan - System Design

## Galilean Telescope Design

- Initial Exploration
- Non inverted image
- Large magnification
  - Low field of view
  - Lower brightness

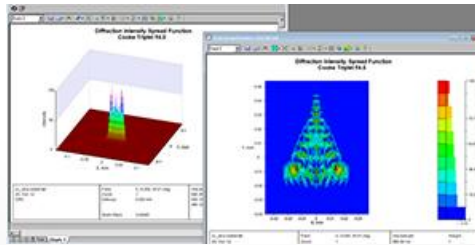
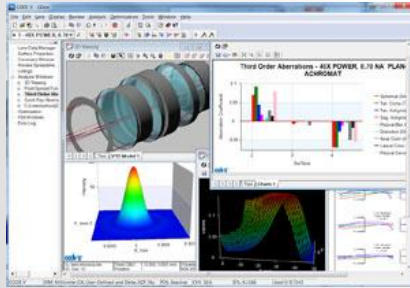




# Testing Design

## CodeV Design Software

- Plan to obtain student license
- Can model, analyze, optimize designs
- Scalability using radiance and irradiance



Images from <http://optics.synopsys.com/codev/>

# Scalability

Radiance

$$L = \int_{\lambda_1}^{\lambda_2} \epsilon \frac{2hc^2}{\lambda^5} \frac{1}{e^{\frac{hc}{k_B T \lambda}} - 1} d\lambda$$

Irradiance

$$E = L\Omega$$

Solid Angle

$$\Omega = \pi \frac{r^2}{d^2}$$

$$E = L\Omega \Rightarrow E = L\pi \frac{r^2}{d^2}$$

Set equal

$$E_{Lab} = E_{Real}$$

$$L\pi \frac{r_{Lab}^2}{d_{Lab}^2} = L\pi \frac{r_{Real}^2}{d_{Real}^2}$$

$$\frac{r_{Lab}}{d_{Lab}} = \frac{r_{Real}}{d_{Real}}$$

Example

$$d_{Real} = r_{Real} \frac{d_{Lab}}{r_{Lab}} = 50m \frac{72in}{2in} = 1800m$$

# Camera Characterization



## FLIR E30 (Forward Looking Infrared)

- Bolometer Resolution : 120x160
- Output Format : Radiometric JPEG
- Visible and IR cameras



## Meteorite

- Weight : approx 5 lbs.
- Composition : Mostly iron
- Diameter : approx 5 inches

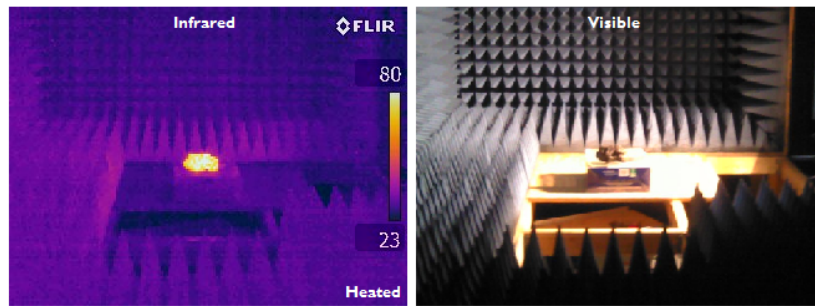
Dec14-12

Dec 14-12

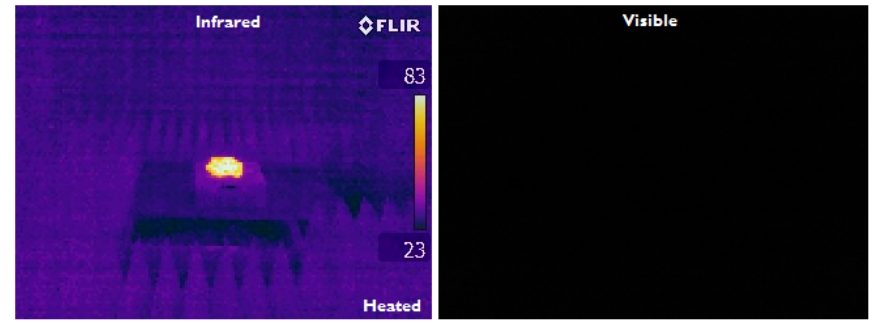
# Camera Characterization

## Preliminary Thermal Measurements

- Heated sample and took images
  - proof of concept.



- Heated with light source



- Heated with no light source

# Obtaining Thermal Info

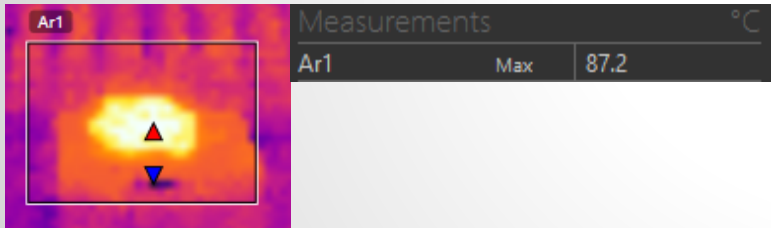
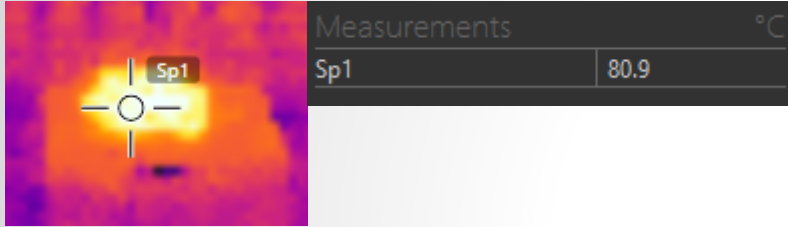
## Thermal distribution

Software Used : MATLAB, FLIR Tools

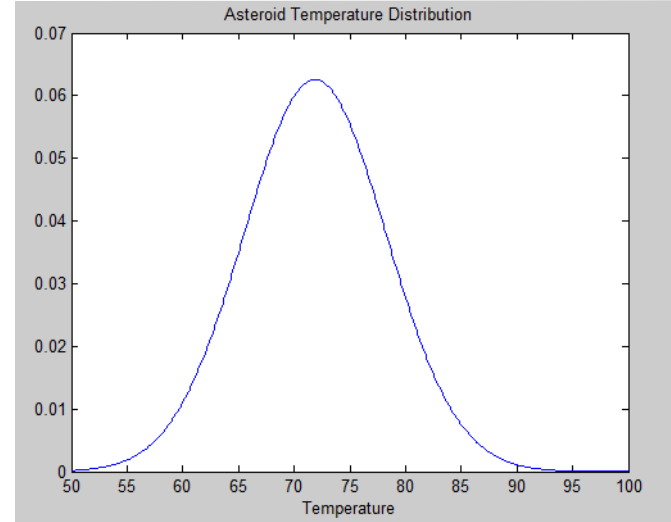
- MATLAB
  - Edge detection
    - localized
    - finds all values within edge
  - Distribution calculations
  - Interpolated temperature from pixel values (no longer needed)
- FLIR Tools
  - Bolometer output (.csv)

# Obtaining Thermal Info

## Flir Tools



## MATLAB



Max Temp : 80 C

# Future Work

- Continue galilean telescope
- Explore other telescope designs
- Bolometer noise considerations
  - Phonon Noise
  - Photon Noise
  - Johnson Noise

# Questions

